

GOKARAJU RANGARAJU INSTITUTE OF ENGINEERING AND TECHNOLOGY

CONTROL SYSTEMS LAB

Course Code: GR15A2045

R15A2045

L:0 T:0 P:2 C:2

Course Objectives

II Year II Semester

- Will have a strong knowledge on MATLAB and Millennium software.
- They get the basic knowledge on practical control system and PLC applications.
- They get the knowledge on applications of machines & electronic devices with control systems.

Course Outcomes

- Will have a strong knowledge of MATLAB software
- Will be able to do various engineering projects.
- Ability to formulate transfer function for given control system problems.
- Ability to find time response of given control system model.
- Plot Root Locus and Bode plots for given control system model
- Ability to design Lead, Lag, Lead-Lag systems in control systems
- Ability to design PID controllers for given control system model

Contents

- 1. Transfer function from zeros and poles
- 2. Zeros and poles from transfer function
- 3. Characteristics of synchros
- 4. Time response of series rlc circuits
- 5. State model from transfer function
- 6. State model from zeros and poles
- 7. Zeros and poles from state model
- 8. Step response of a transfer function
- 9. Impulse response of a transfer function
- 10. Ramp response of a transfer function
- 11. Step response of a state model
- 12. Impulse response of a state model
- 13. Ramp response of a state model
- 14. Transfer function of a dc generator

GR15 Regulations (2015-16)



- 15. Transfer function of a dc motor
- 16. Time response of second order system
- 17. Root locus from a transfer function
- 18. Bode plot from a transfer function
- 19. PID controller
- 20. Lag compensator
- 21. Lead compensator
- 22. Lag-lead compensator
- 23. Determination of transfer function of dc motor
- 24. Hysteresis control of speed and current of dc motor, output to keep armature current Within limits using lab view
- 25. Bang bang speed control of dc motor
- 26. Speed control of dc motor using PID controller with a tcho feedback
- 27. Experimental determination of frequency response of speed control of a dc motor and to Obtain the transfer function of the system using lab view
- 28. Nyquist plot from transfer function
- 29. Ac variable speed drive for 3 phase induction motors from 0.25kw to 7.5kw, 0.33hp To 10hp.
- 30. Millenium PLC applications